

LA-UR-13-20777

Approved for public release; distribution is unlimited.

Title: Stabilizing a laboratory plasma column beyond the external kink limit

Author(s): Sears, Jason A.
Intrator, Thomas P.
Wurden, Glen A.

Intended for: invited colloquim



Disclaimer:

Los Alamos National Laboratory, an affirmative action/equal opportunity employer, is operated by the Los Alamos National Security, LLC for the National Nuclear Security Administration of the U.S. Department of Energy under contract DE-AC52-06NA25396. By approving this article, the publisher recognizes that the U.S. Government retains nonexclusive, royalty-free license to publish or reproduce the published form of this contribution, or to allow others to do so, for U.S. Government purposes. Los Alamos National Laboratory requests that the publisher identify this article as work performed under the auspices of the U.S. Department of Energy. Los Alamos National Laboratory strongly supports academic freedom and a researcher's right to publish; as an institution, however, the Laboratory does not endorse the viewpoint of a publication or guarantee its technical correctness.

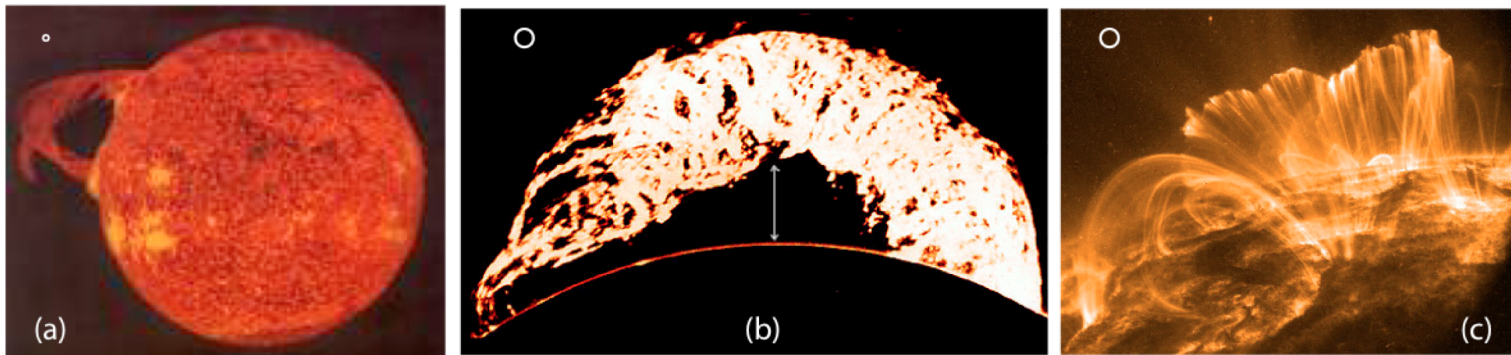
Stabilizing a laboratory plasma column beyond the external kink limit

Jason Sears

Los Alamos National Laboratory

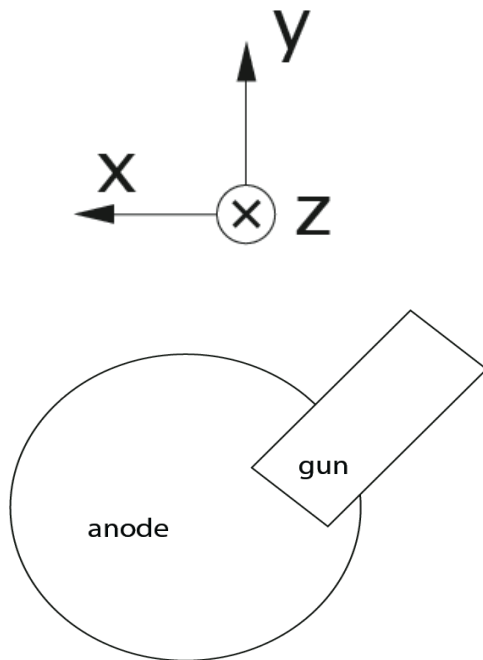


emerging flux ropes may also display kink instabilities



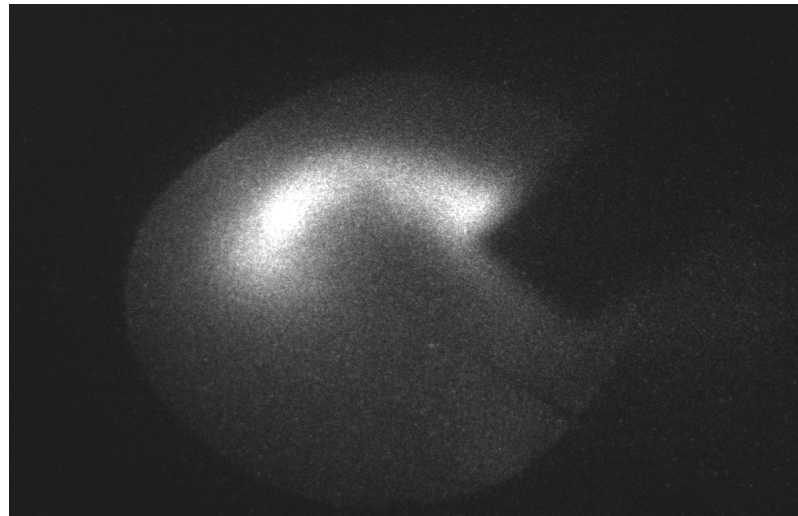
the sawtooth in a tokamak is also a kink mode

the RSX current-driven kink mode saturates at finite amplitude



axial perspective

the kink gyrates at a steady rate, indefinitely



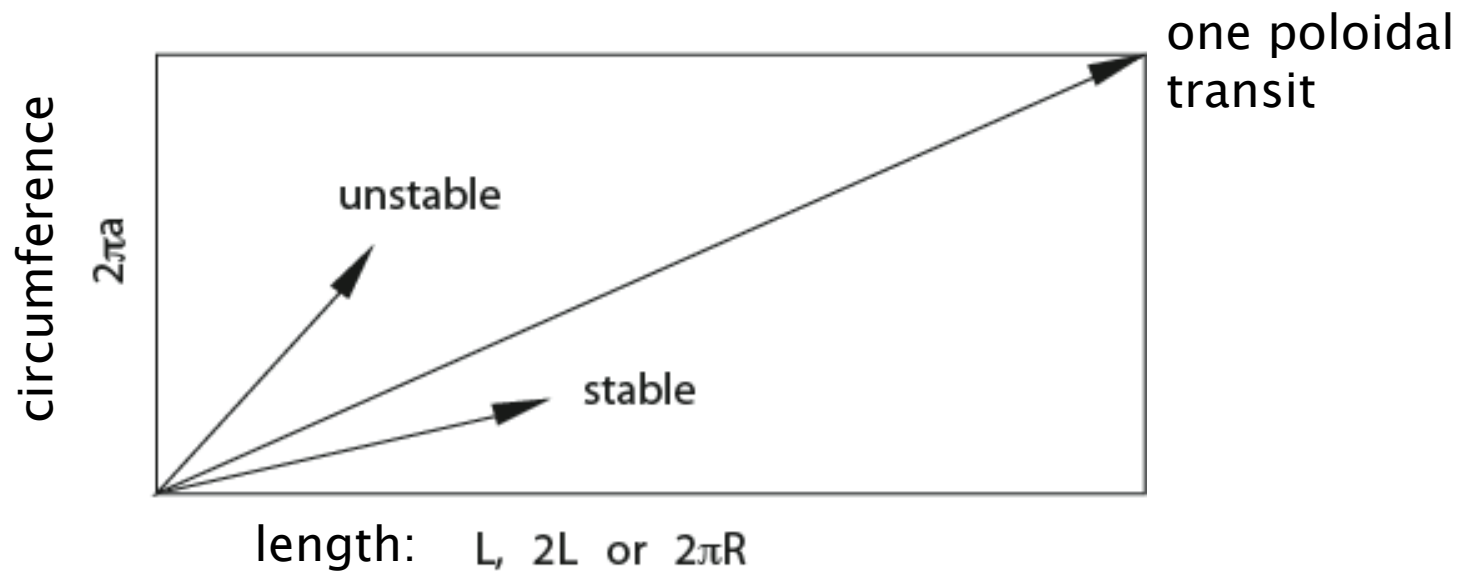
do kink instabilities in astrophysical flux ropes also saturate?

in this talk:

- kink instability from field line twist
- potential causes of saturation of the kink instability
- Reconnection Scaling Experiment (RSX)
- 3D measurements suggest current above the kink threshold; present insight

the kink arises when twist in magnetic field is too great (linear model)

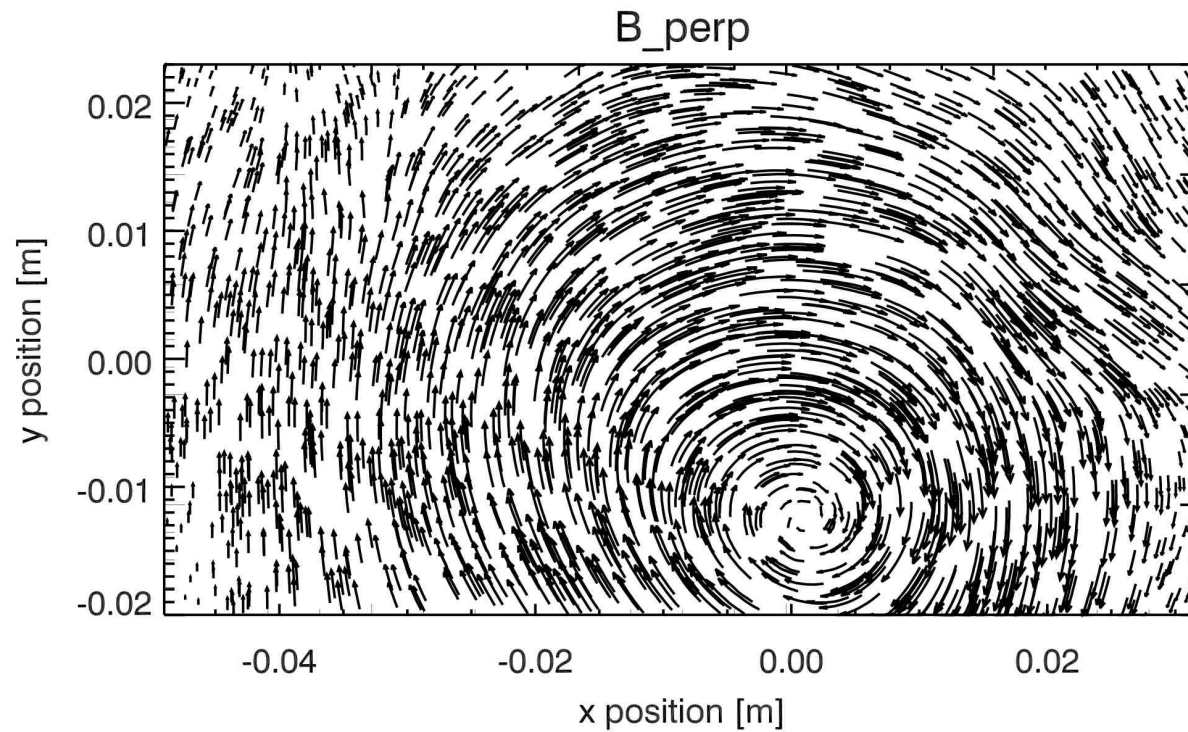
$$J_{ks} = \frac{4\pi B}{\mu_0 L}$$



the kink handedness is paramagnetic
kink pitch is not constant
flow causes gyration; sense depends on $k/|k|$
growth is unbounded

B_{perp} is measured over entire cross-section

→
0.006 T



in RSX under precise conditions, the kink can persist at small amplitudes for long timescales

potential causes of saturation

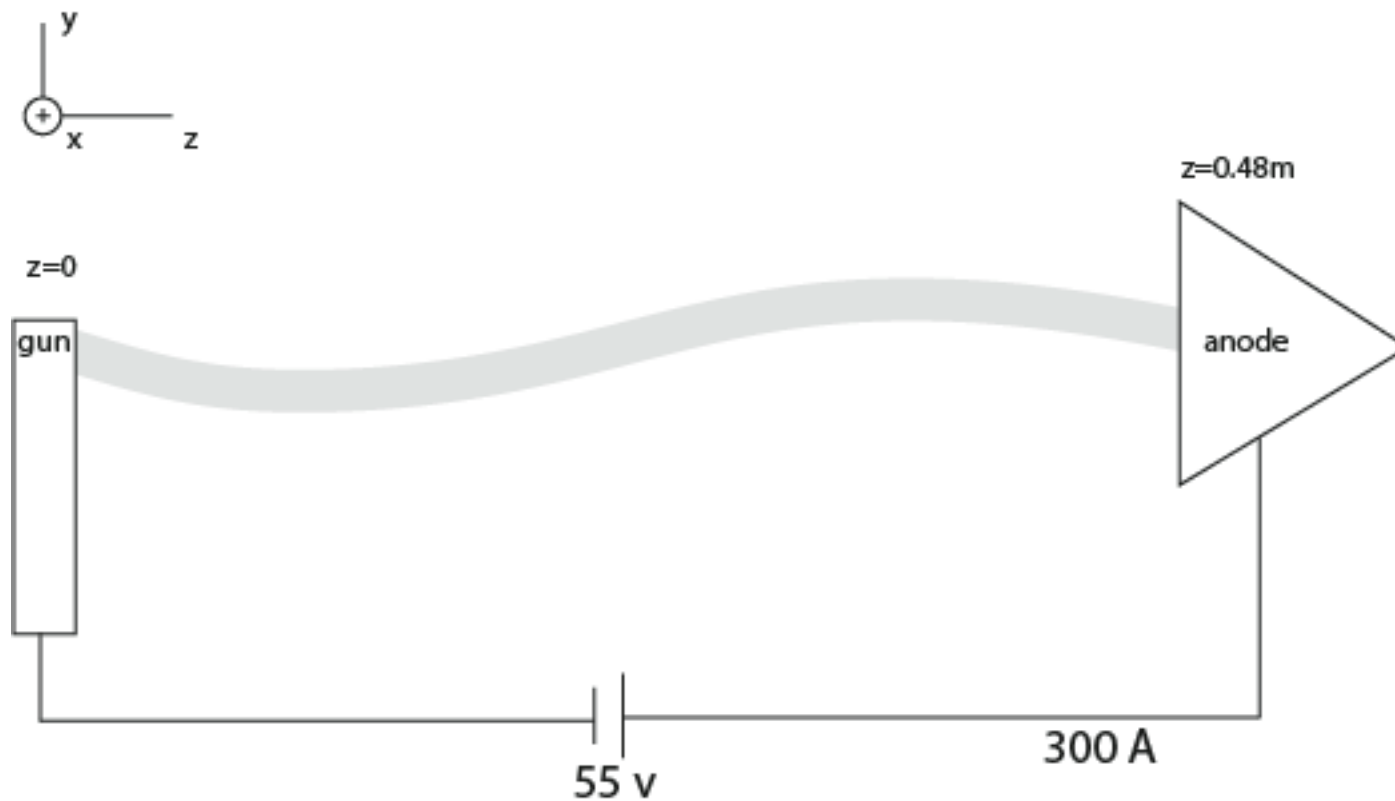
- conductive wall (image current feedback)
- aperiodicity (tension from line-tied footpoints)
- nonlinear MHD (finite amplitude)
- two-fluid effects (separation of mass and current)
- kinetic effects (collisionality is weak)
- secondary instabilities (gravity, islands)

geometry of the gun/anode/diagnostic system

slow, visible light image of a discharge

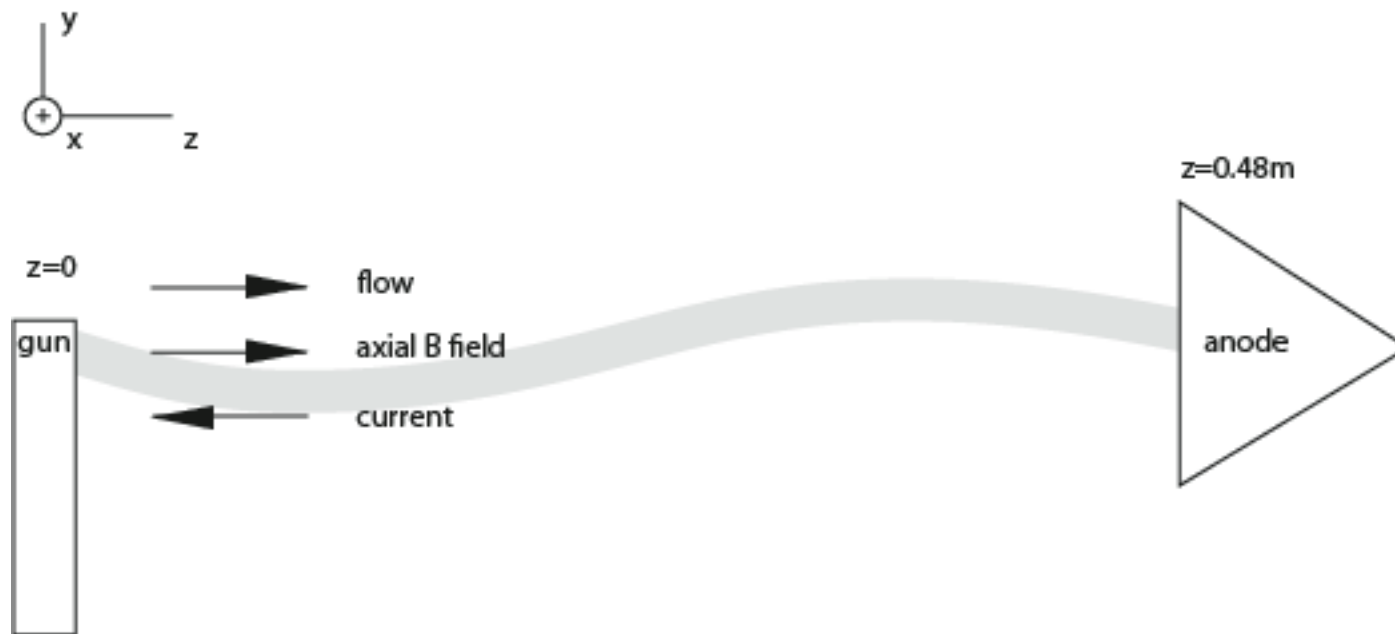


geometry of the gun/anode/diagnostic system



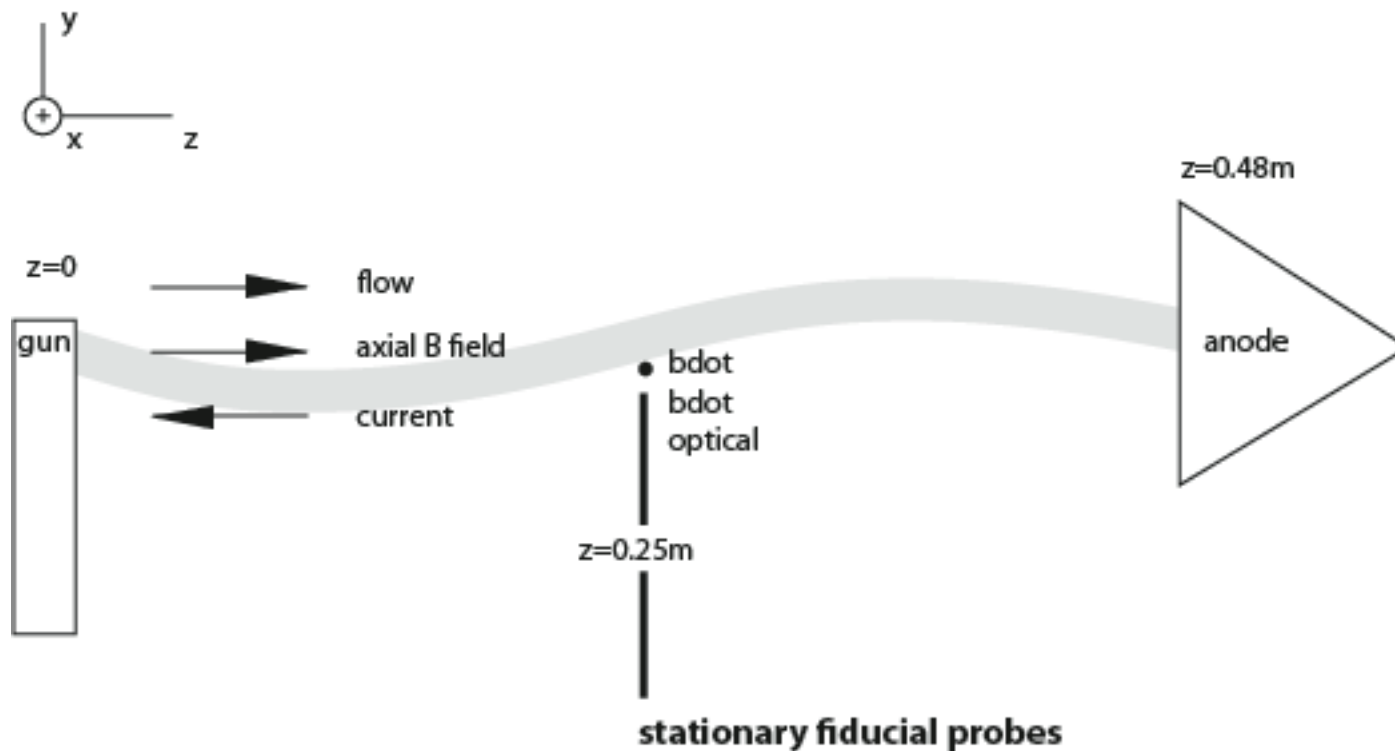
plots in this talk will be in xy planes at various z

geometry of the gun/anode/diagnostic system



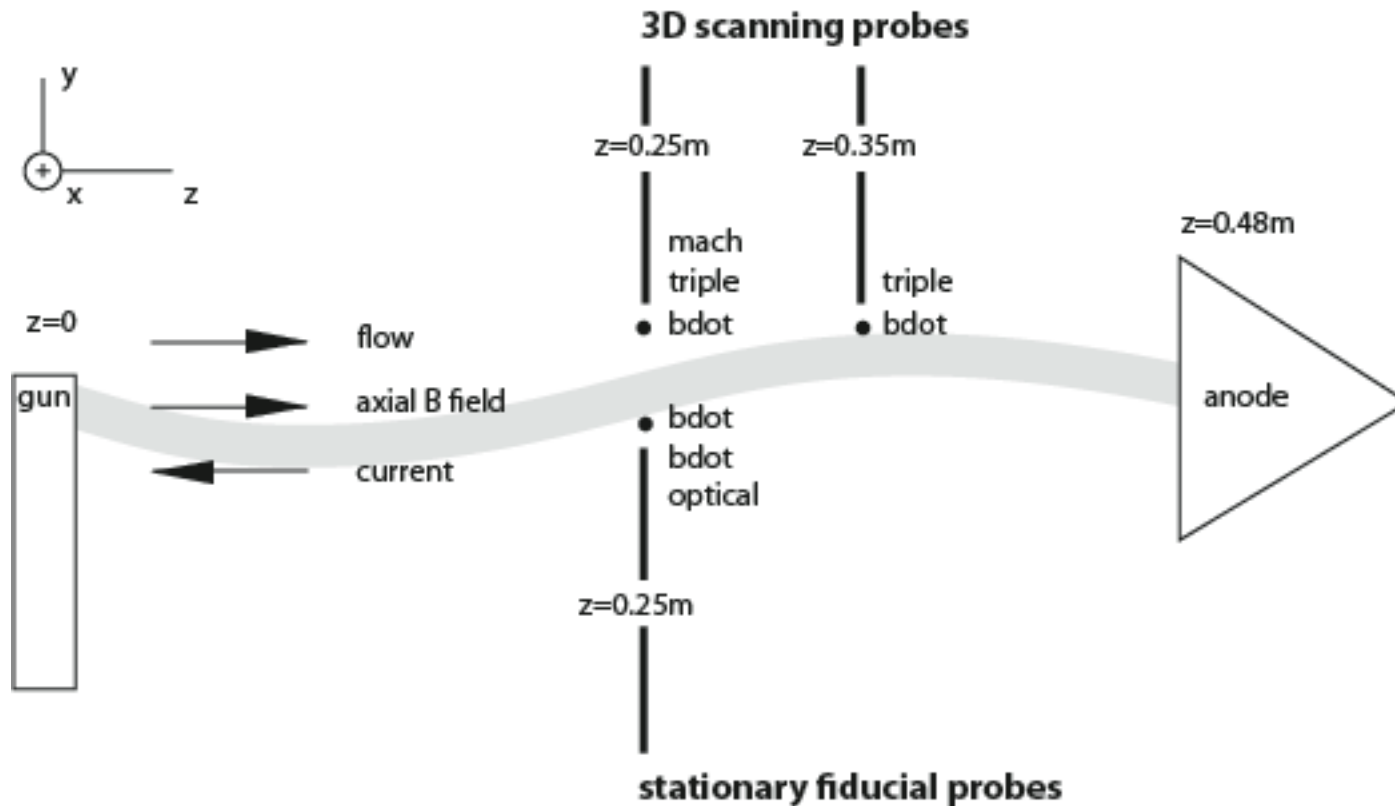
current opposite field leads to left-handed kinks

geometry of the gun/anode/diagnostic system



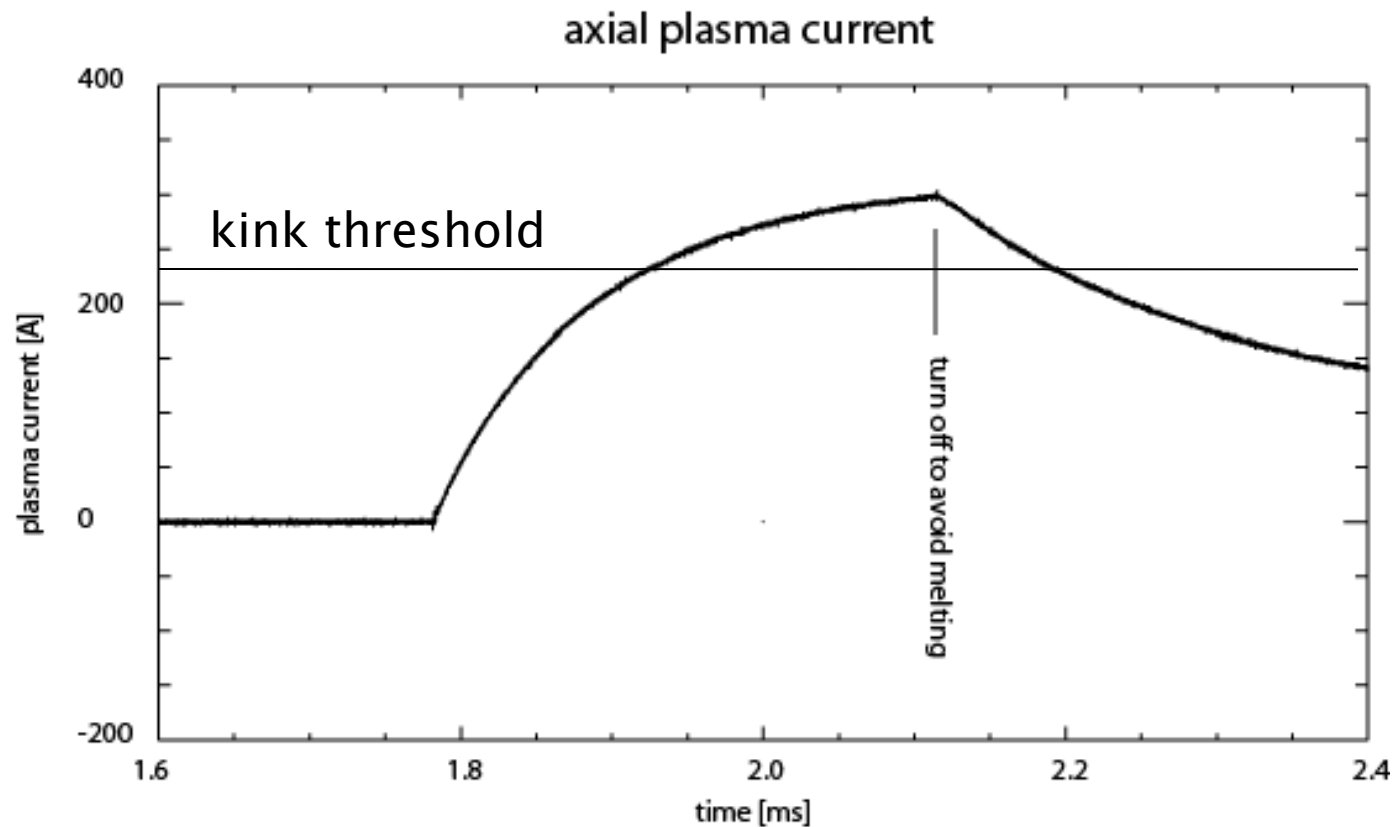
stationary probes serve to register time base between shots

geometry of the gun/anode/diagnostic system



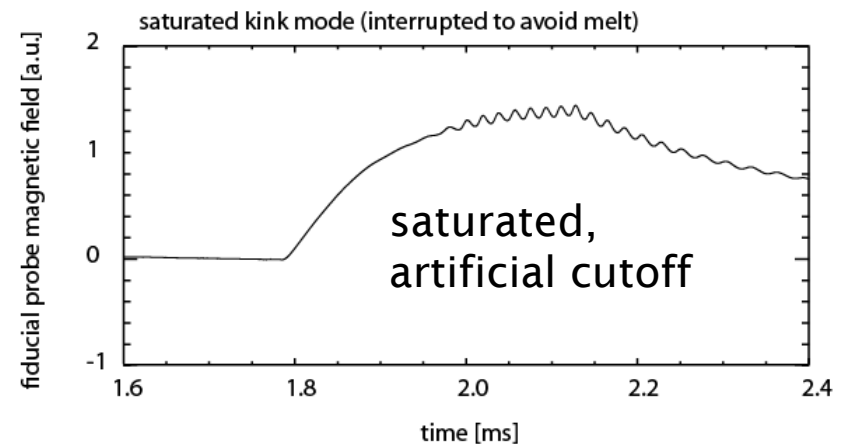
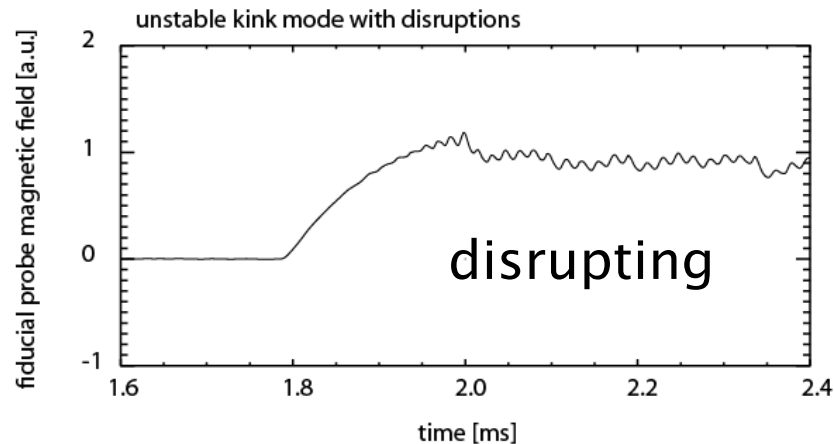
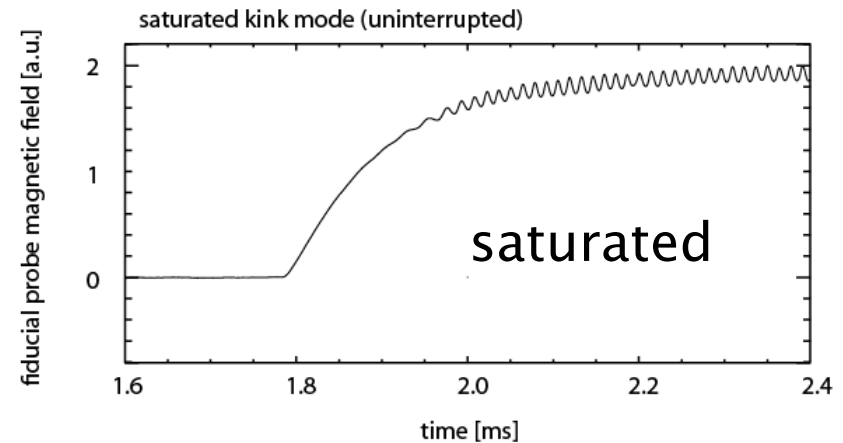
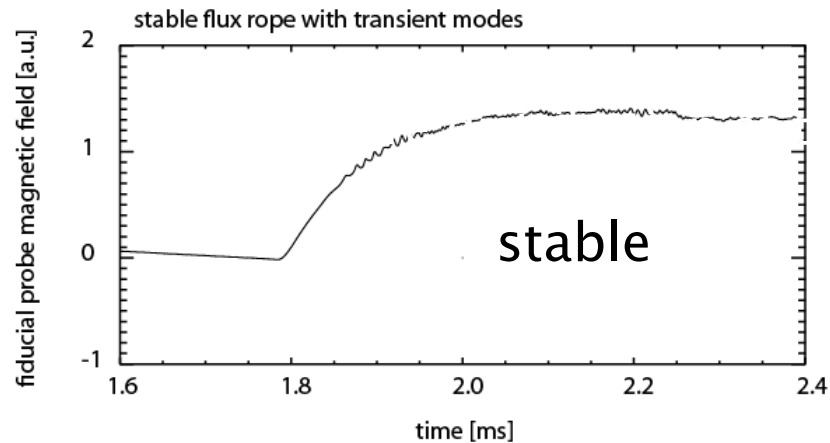
a 3D volume is reachable
stationary probes serve to register time base between shots
plots in this talk will be in xy planes at various z

A plasma current is set up just beyond the external kink limit



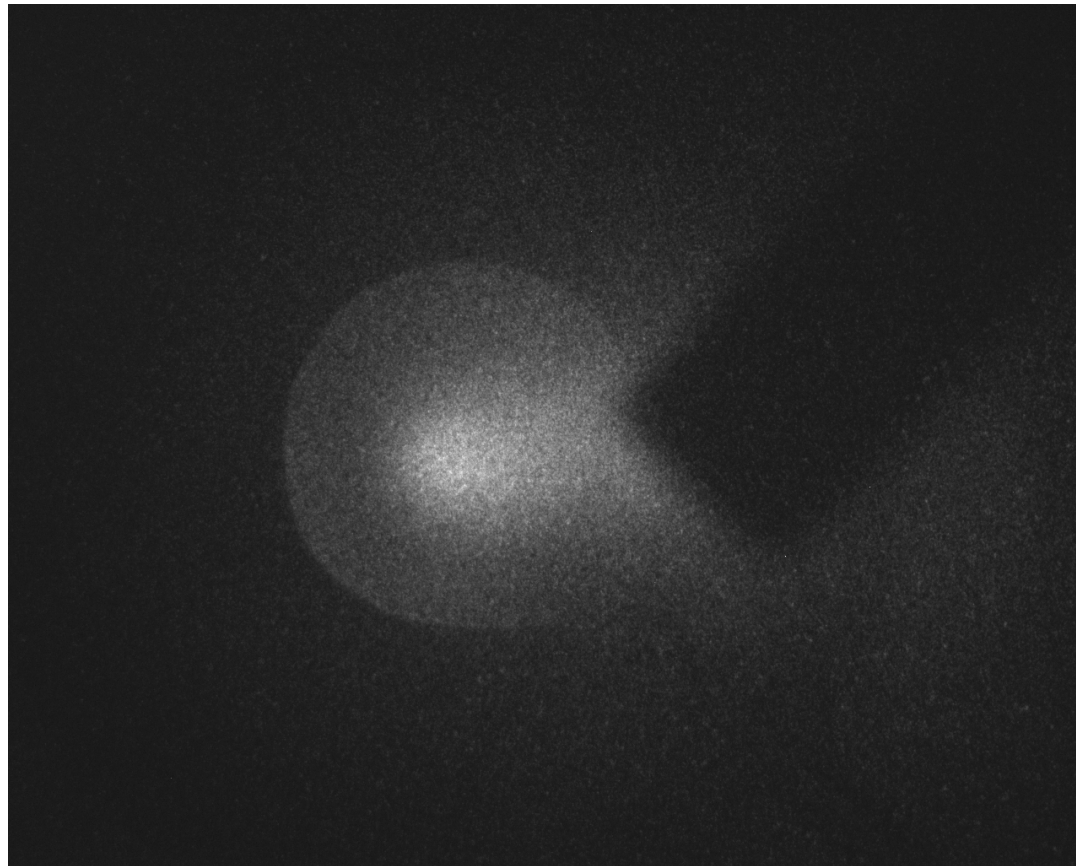
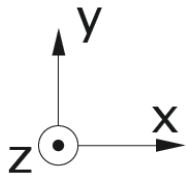
axial magnetic field (300 G) is essentially static
plasma turns on at early time
plasma current drawn once discharge established
plasma current terminated early to avoid melt

the flux rope can stay stable, disrupt, or attain a saturated oscillation



marginal stability threshold depends on line-tiedness
high frequency mode sometimes appears
disruption occurs when flux rope jumps over anode
experiment artificially shortened to avoid melt damage

disruption of kink unstable flux rope with unbounded growth beyond anode, end view



conditional sampling composites structure over many repeatable discharges

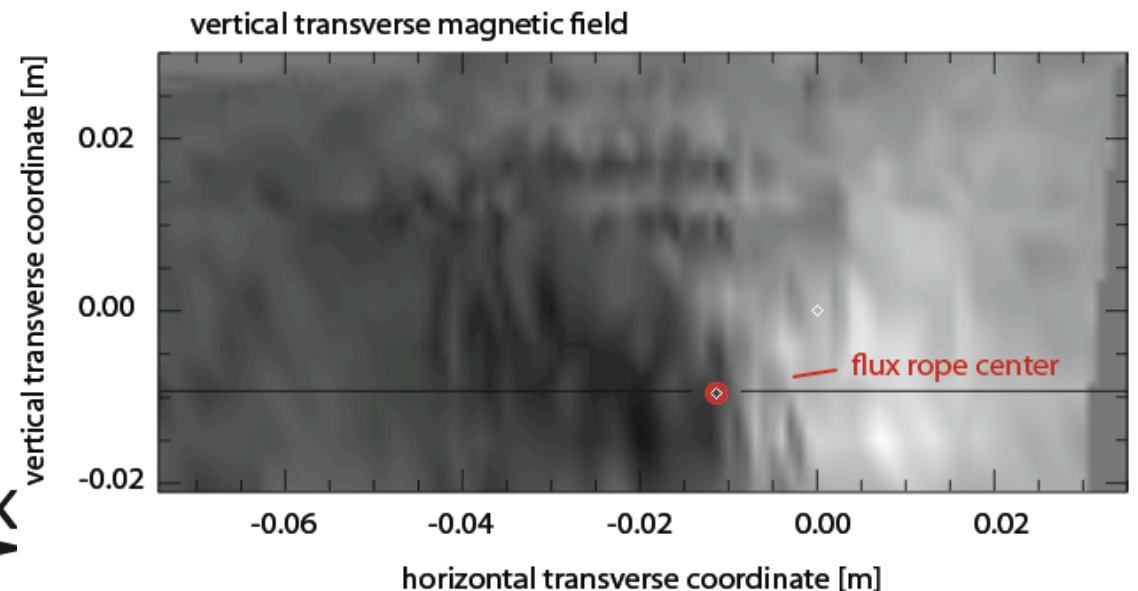
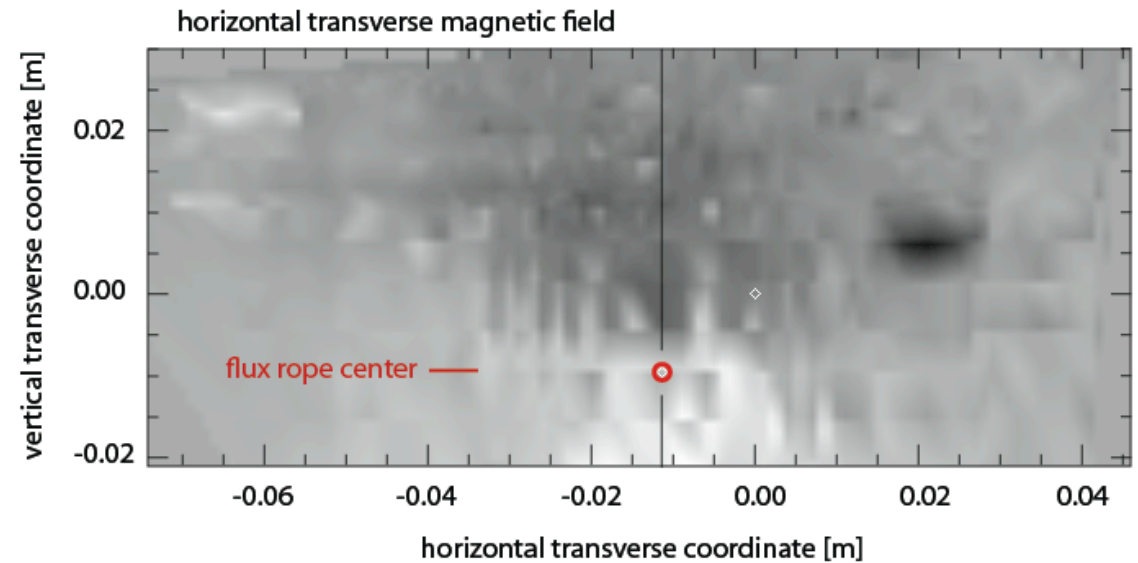
fiducial probes capture onset of event (gyrating flux rope)

event is aligned in time from shot to shot

scanned probes sample 3D volume over series of shots

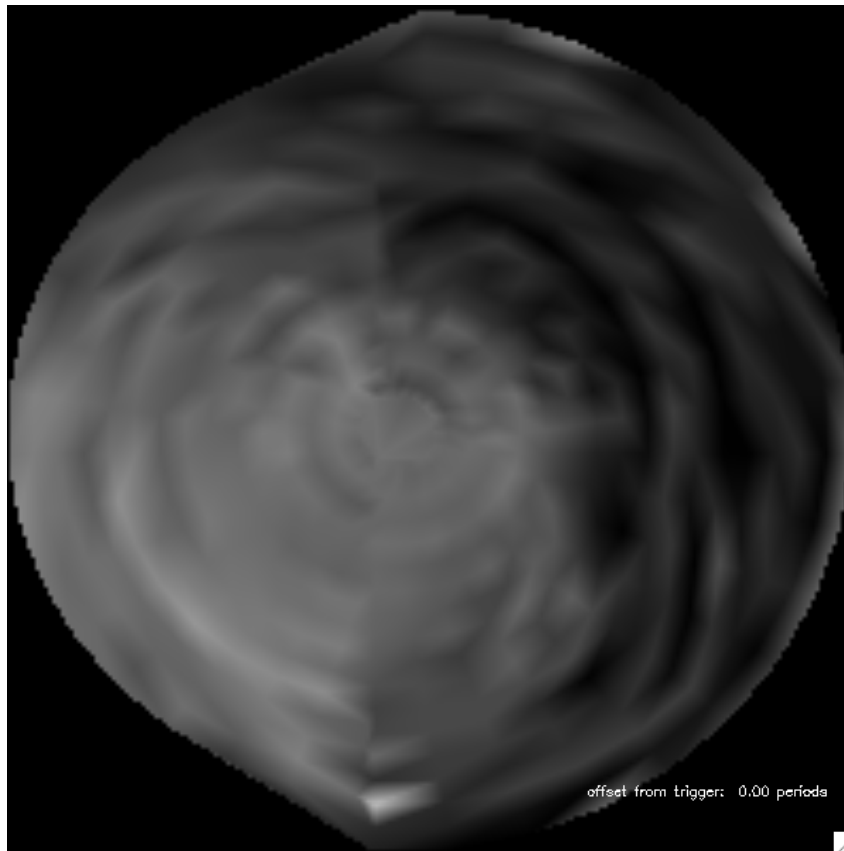
3D sequence is measured

center of gyration and sense of rotation is established



the mach number has a much broader distribution than the density

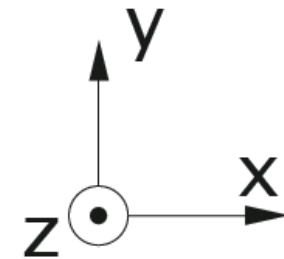
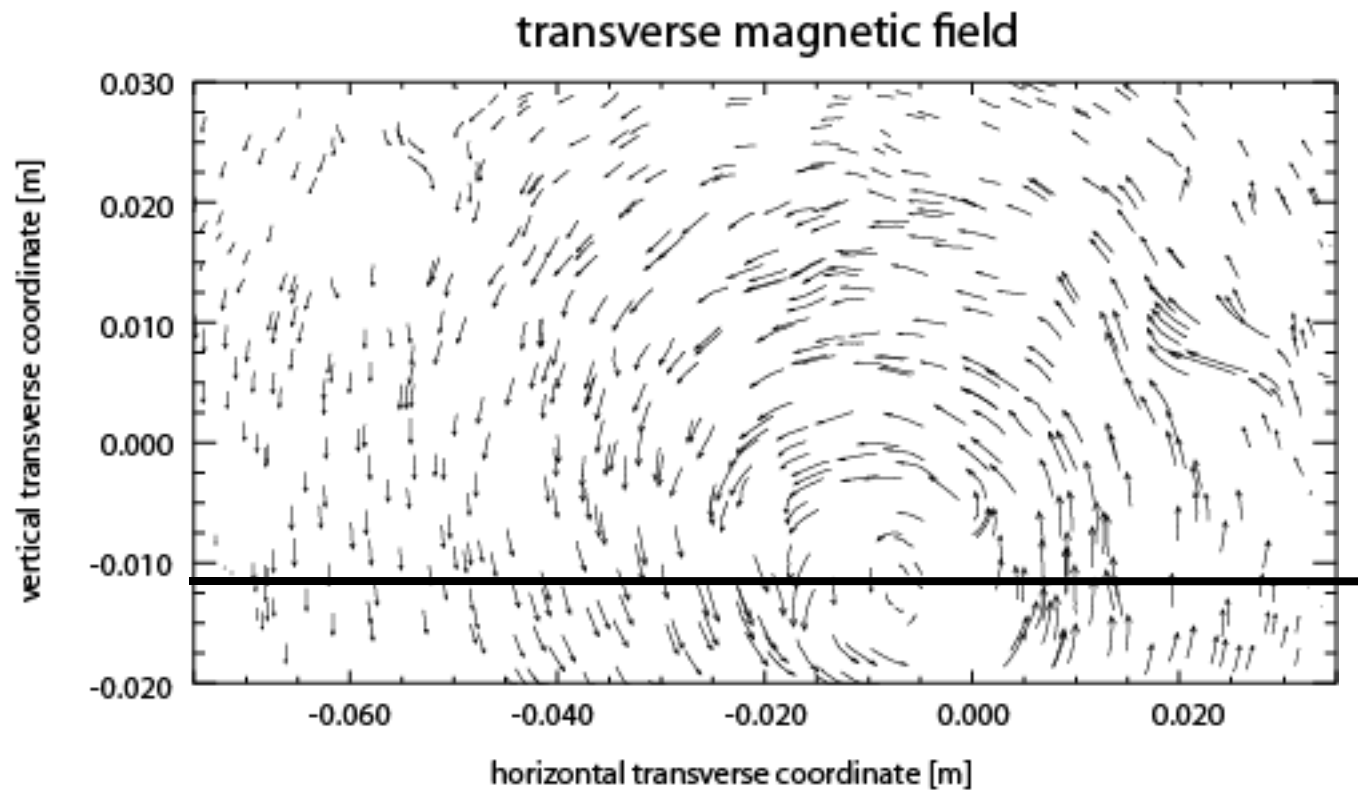
mach number distribution (white is 1)



shear in flow may generate quadrupole signature (see Intrator, next talk)

shear may also lead to secondary instabilities

combining horizontal and vertical measured fields shows a magnetic profile expected for a compact current profile



current density
calculated along
this chord
(next slide)

physics outline

problem: the kink saturates at steady, finite amplitude

explanations:

internal vs external

wall stabilization

effect of flow

momentum balance

bifurcated equilibria

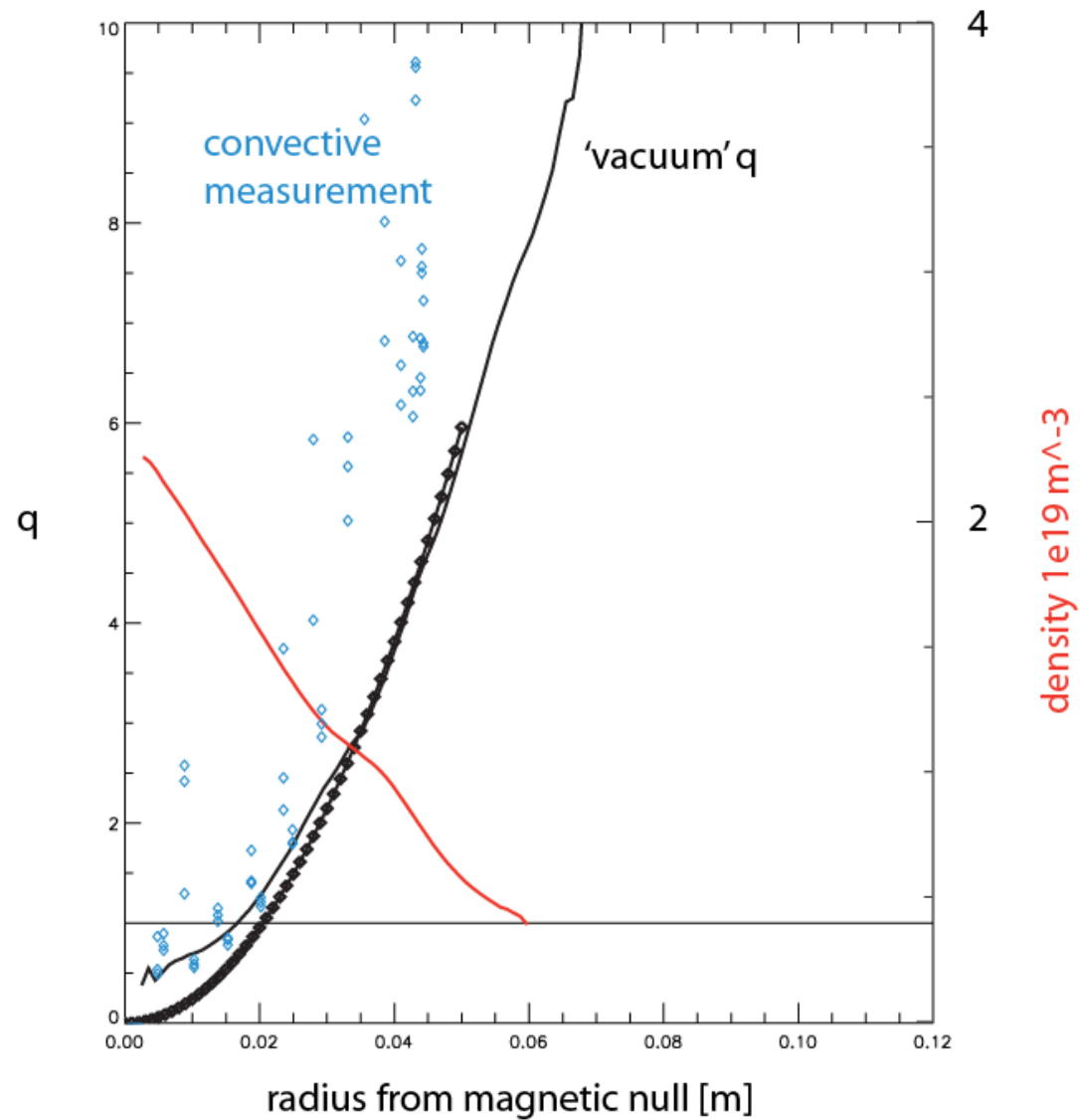
inertial forces

internal vs external

an internal kink has $k \cdot B = 0$ in the plasma and requires reconnection on that surface to grow. it becomes a tearing mode.

RosenbluthPhysFluids16 1894 showed that this can cause an internal kink to saturate

density profile shows $q=1$ resonant surface is well within the plasma



wall stabilization

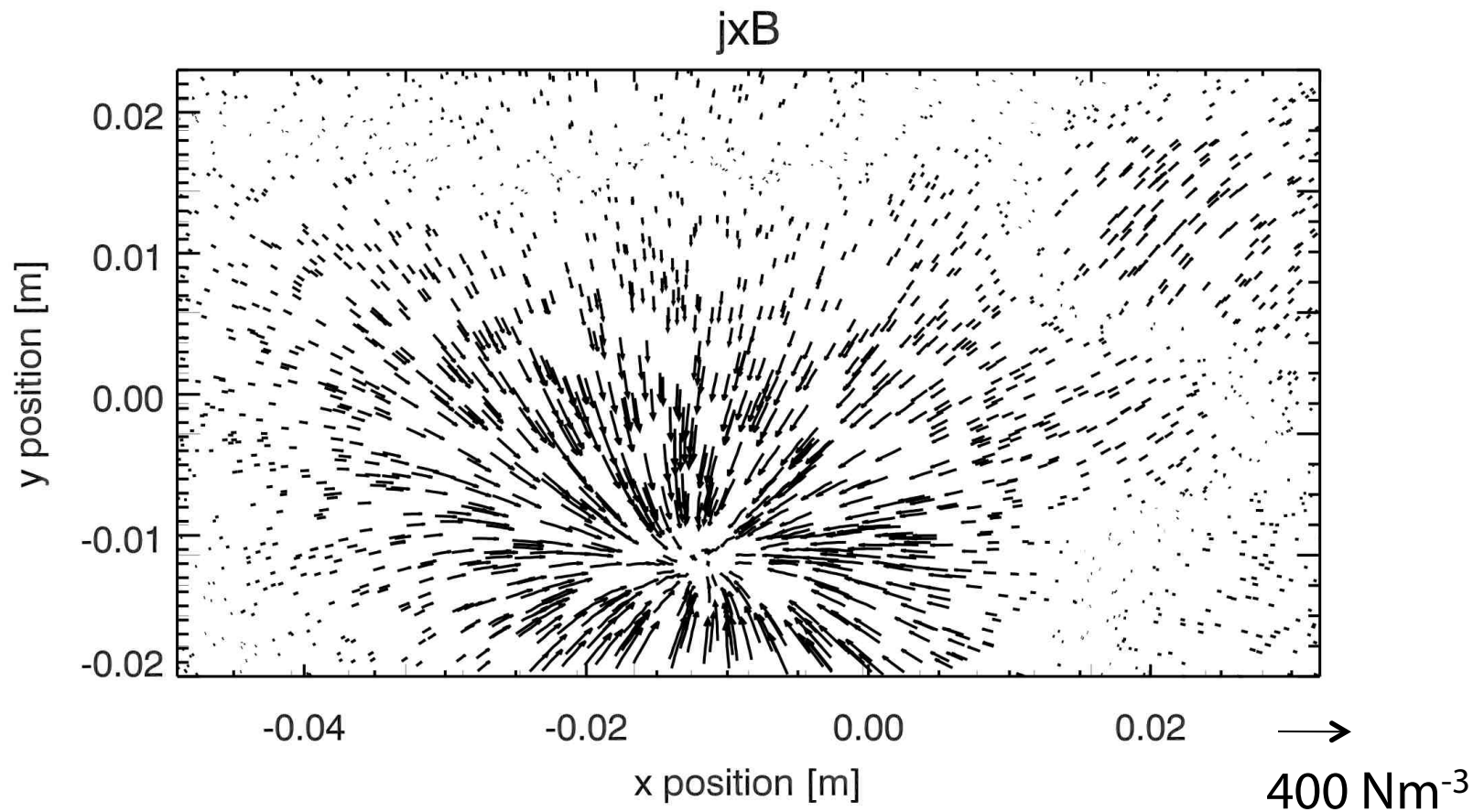
walls minimize the vacuum energy available to an instability.
our wall is far away from the plasma, so it does not contribute to stability

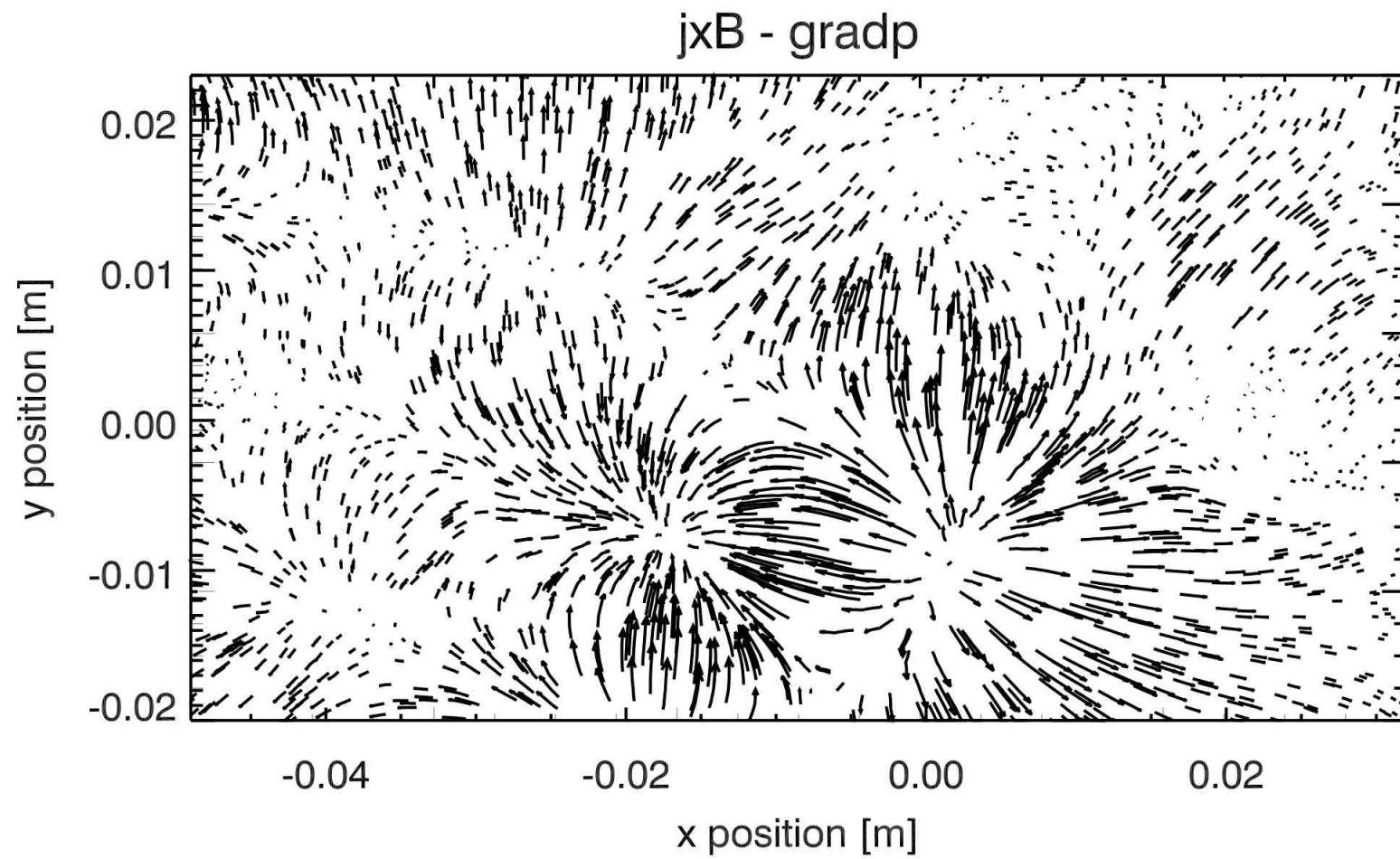
flow

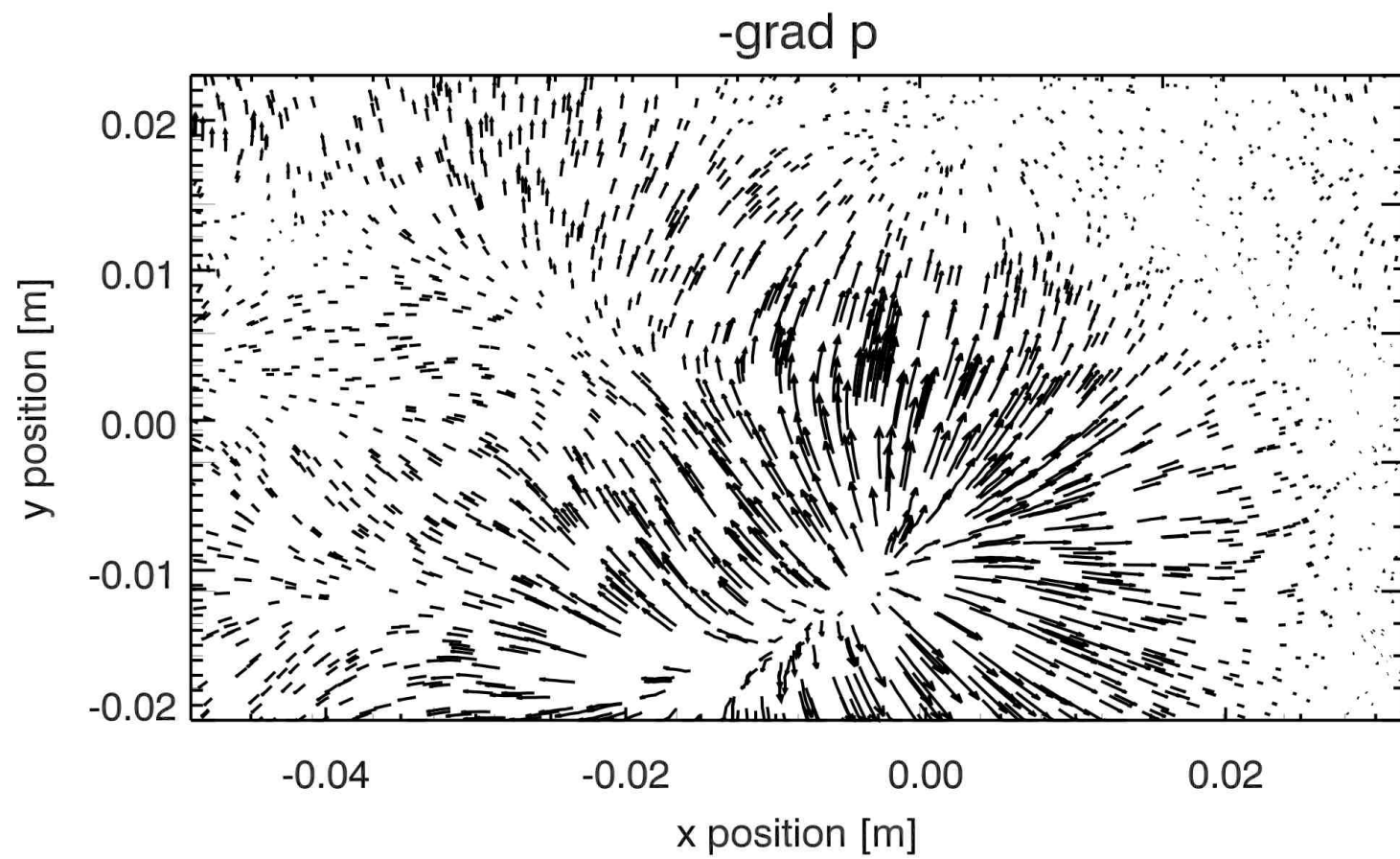
flow causes the kink mode to rotate

shear flow can stabilize the kink
(ShumlakPhysPlasPRL 75 3285)

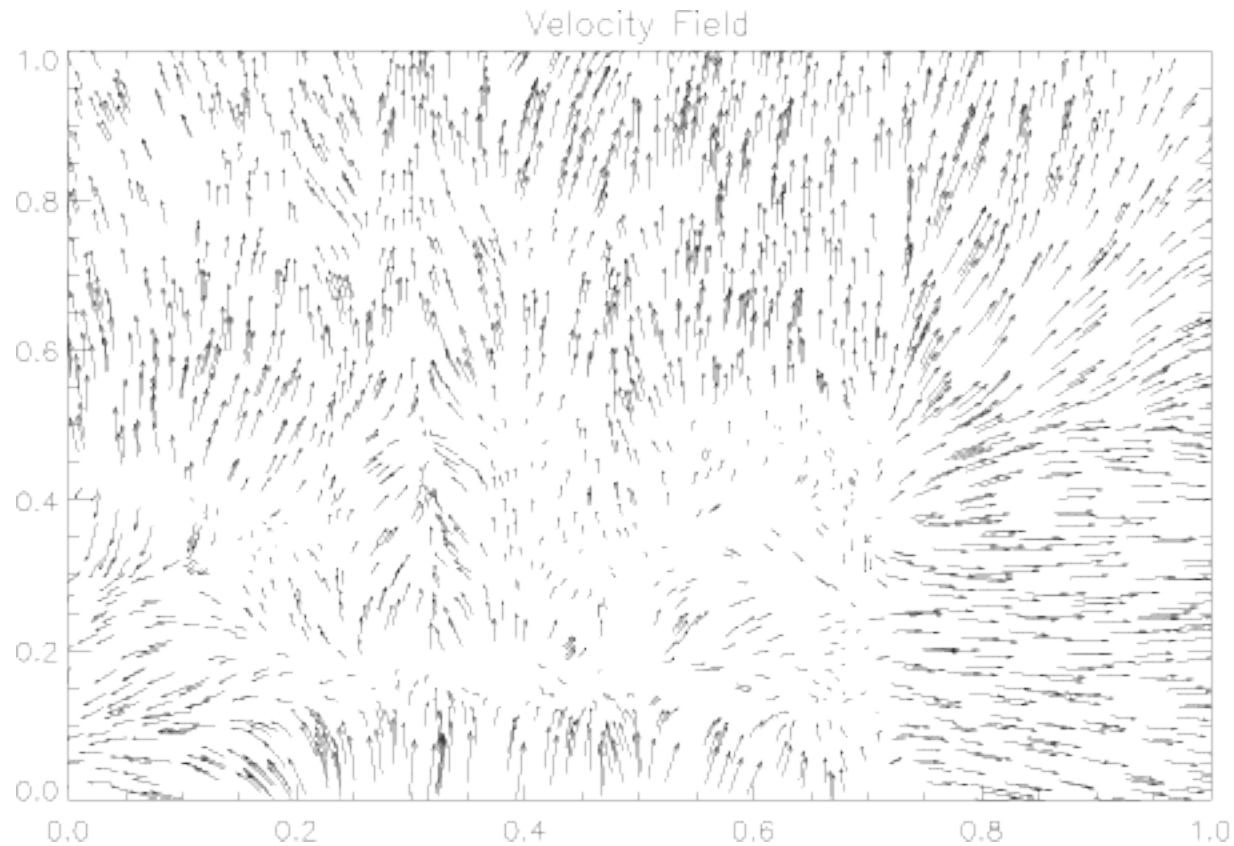
$J \times B_{\text{perp}}$ measured over entire cross section

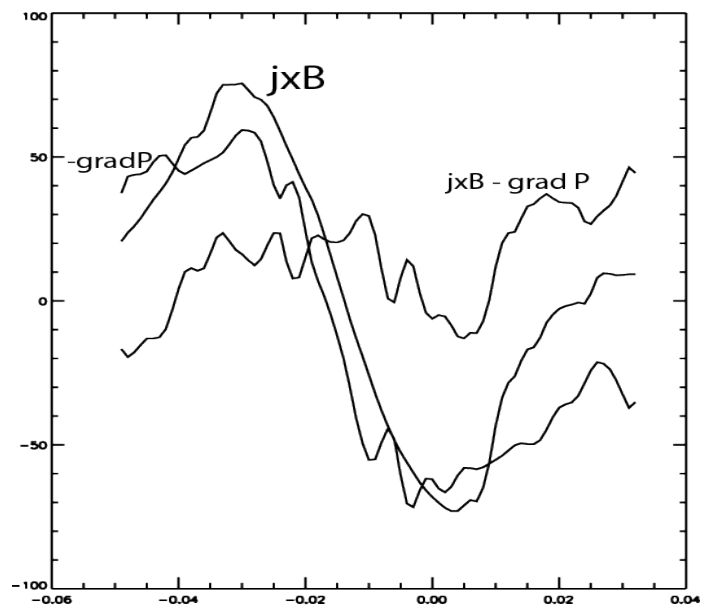
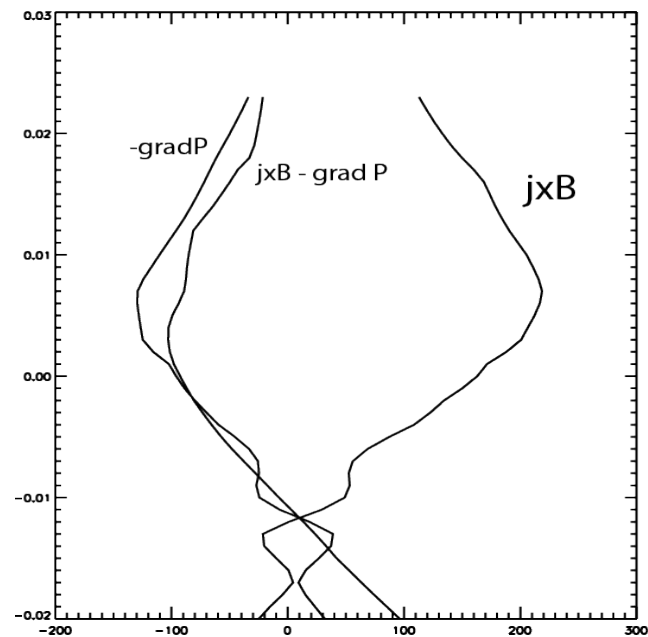
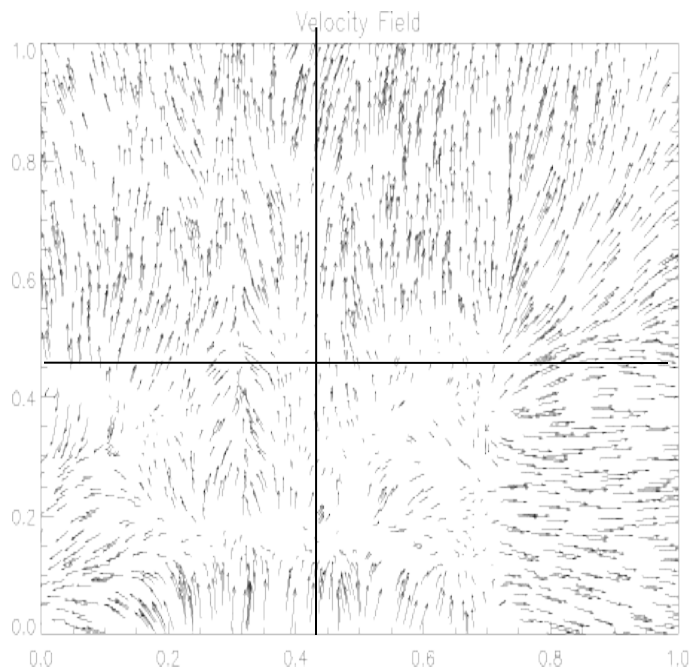






momentum balance:
 $\rho \cdot dv/dt = \sigma E + j \times B - \text{grad} P$





conclusion

- the kink mode can be unstable in the RSX plasma
- the kink saturates in a small range of current density
- RSX allows 3D measurement of field and plasma
- current density is measured above stability limit
- contours in density and temperature are not coincident

bifurcated equilibria

- Rutherford (IAEA 1971) finds an equilibrium for an external kink mode

inertial forces

- the kink is solved in inertial frame
- when it rotates due to flow, the new solution is the sum of inertial solution plus coriolis and centrifugal forces
- (careyApJ699 362)